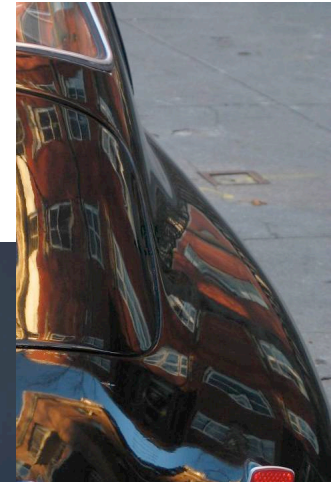
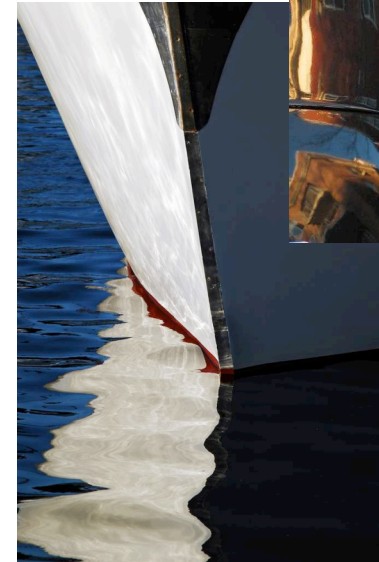




Shape Optimization Using Reflection Lines

Elif Tosun
Yotam I. Gingold
Jason Reisman
Denis Zorin
New York University

Reflections



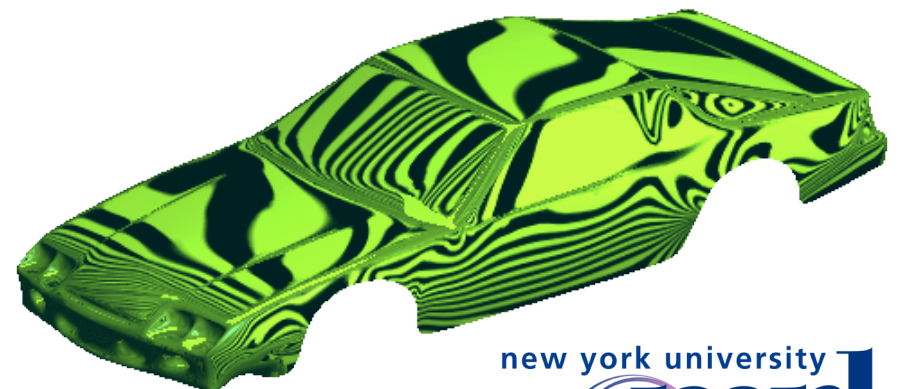
- are sensitive to surface shape
- depend on local quantities
- depend on viewer location



“Cloud Gate”
Anish Kapoor

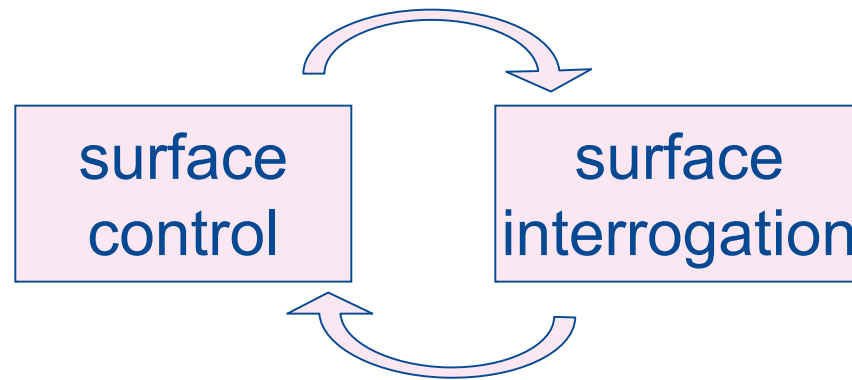
Reflection Lines

- Capture aspects of general reflections
- Show surface imperfections better than lighting only
- Tool for surface quality assessment
- Interactive rendering, easy to implement



Problem

- Surface quality and shape design complimentary
- Control of shape has indirect effect on quality



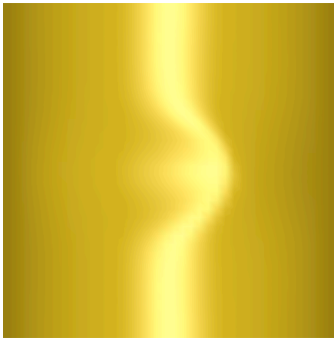
Formulate surface editing as an optimization problem

Problem

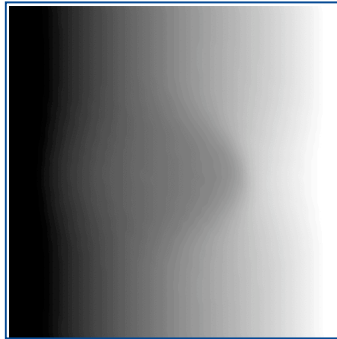
Surface Interrogation



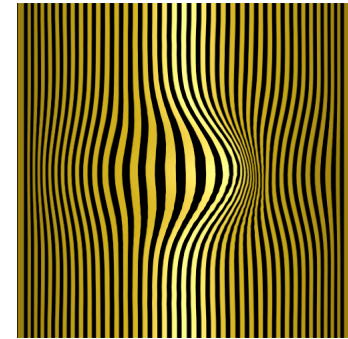
Surface f



Reflection Function $\theta(f)$



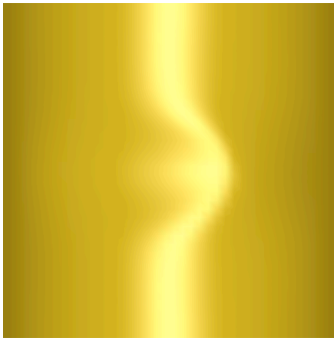
Reflection Lines



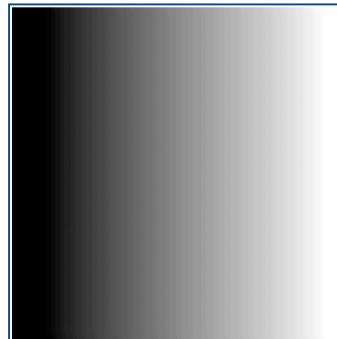
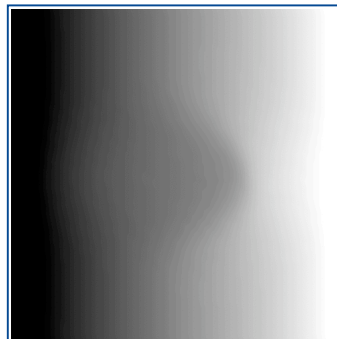
Problem

Surface Interrogation

Surface f

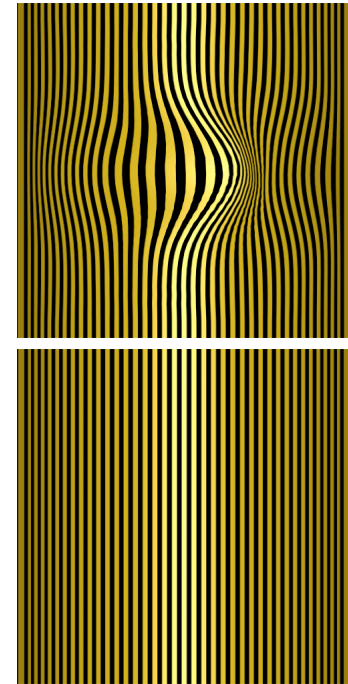


Reflection Function $\theta(f)$



User defined
Reflection Function θ^*

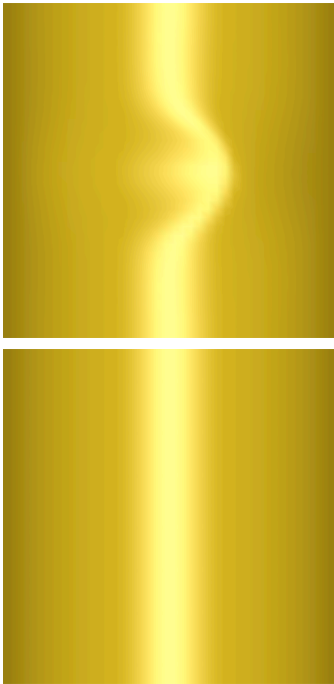
Reflection Lines



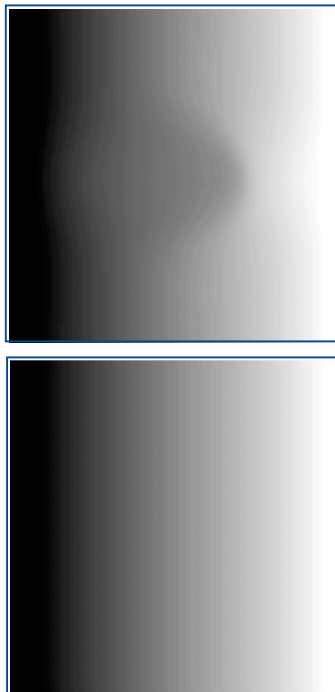
Problem

Surface Interrogation

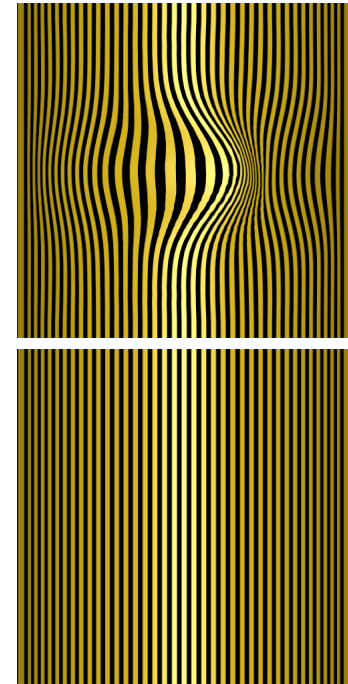
Surface f



Reflection Function $\theta(f)$



Reflection Lines

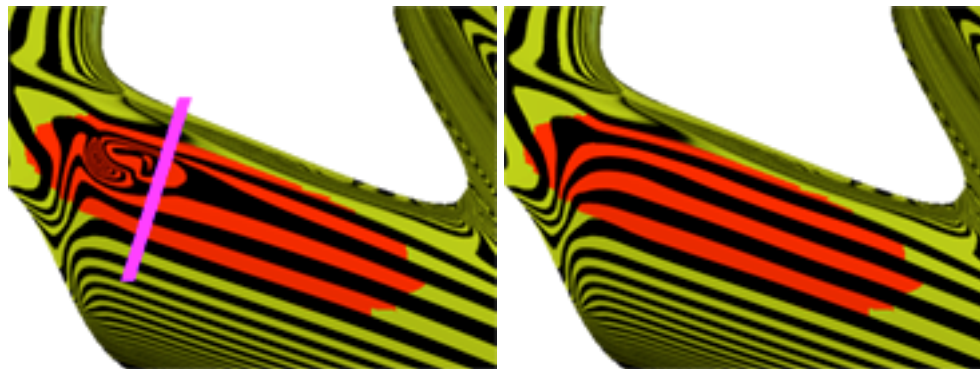


User-defined
Reflection Function θ^*

$$\int (\theta(f) - \theta^*)^2 \rightarrow \min$$

Our Solution

- Interactive surface modeling tool based on reflection line optimization
- Mesh based - discretization of reflection lines
- Smoothing, warping, changing line density and direction, image based reflection



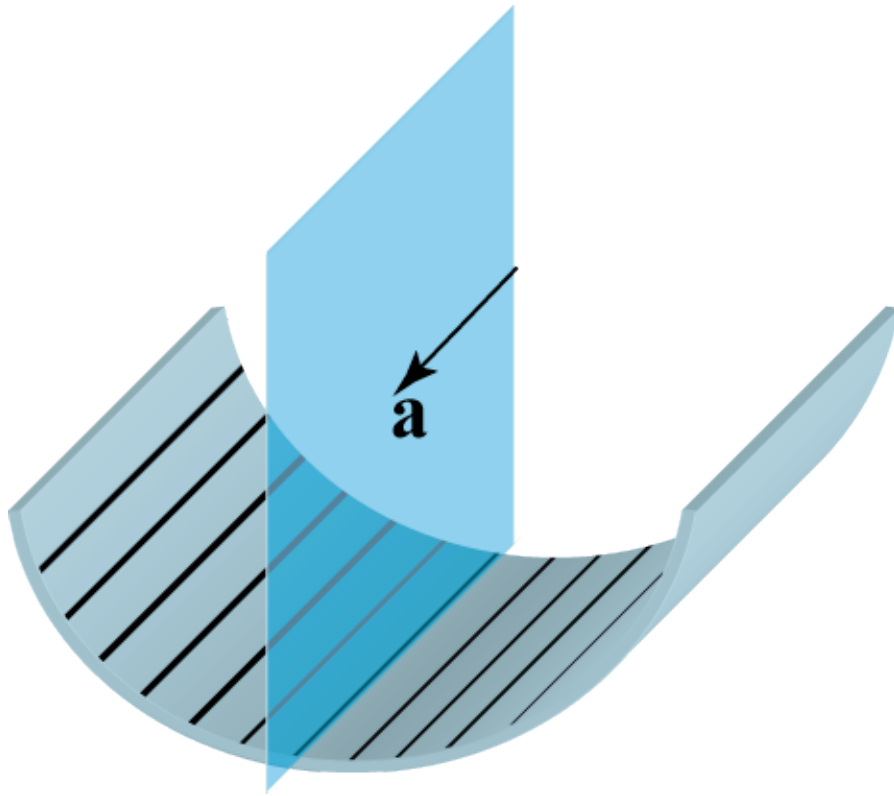
Approach

- Local parameterization over image plane
- Triangle-based discretization of derivatives

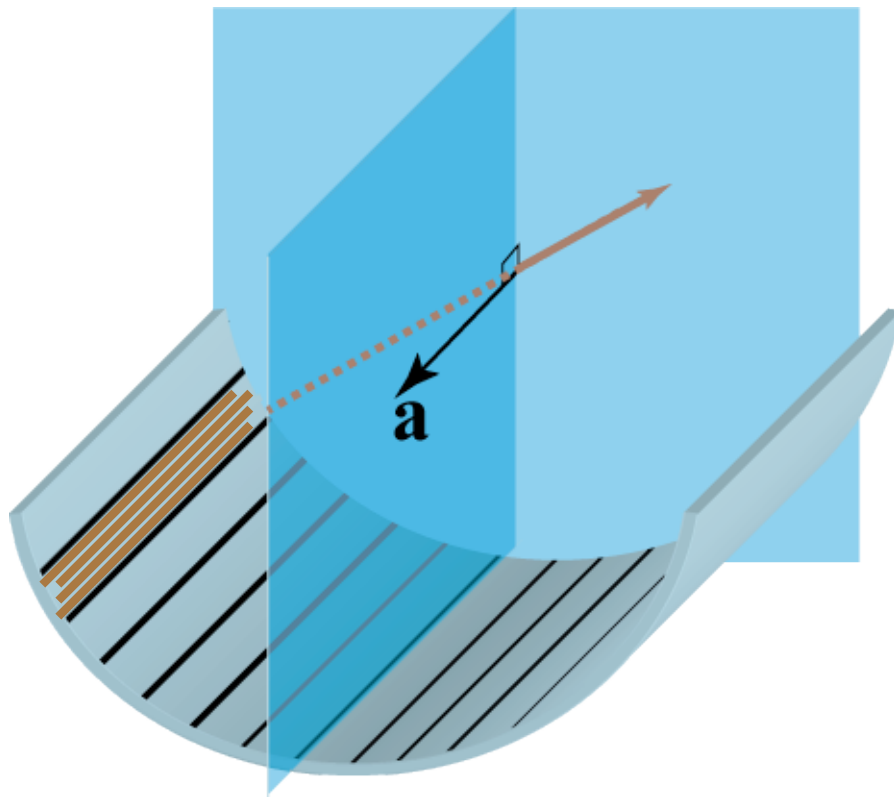
Related Work

- Klass 1980
 - differential-geometric description
- Horn 1986
 - shape from shading
- Loos, Greiner and Seidel 1999
 - reflection lines on NURBS
- Hildebrandt, Polthier and Wardetzky 2005
- Grinspun, Gingold, Reisman and Zorin 2006
 - discrete shape operators

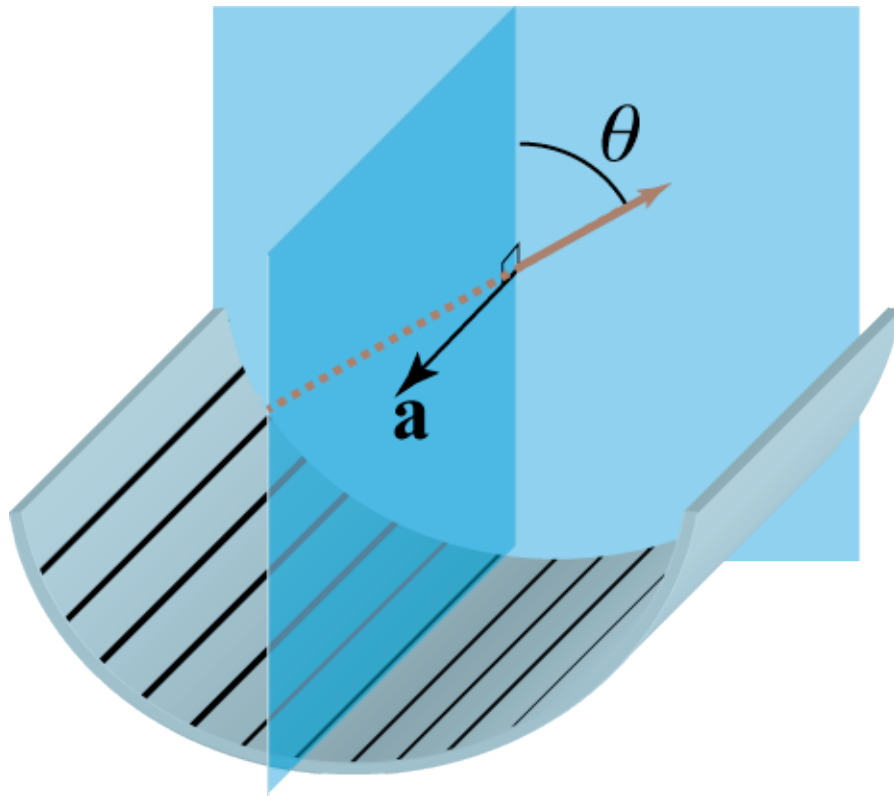
Reflection Line Function



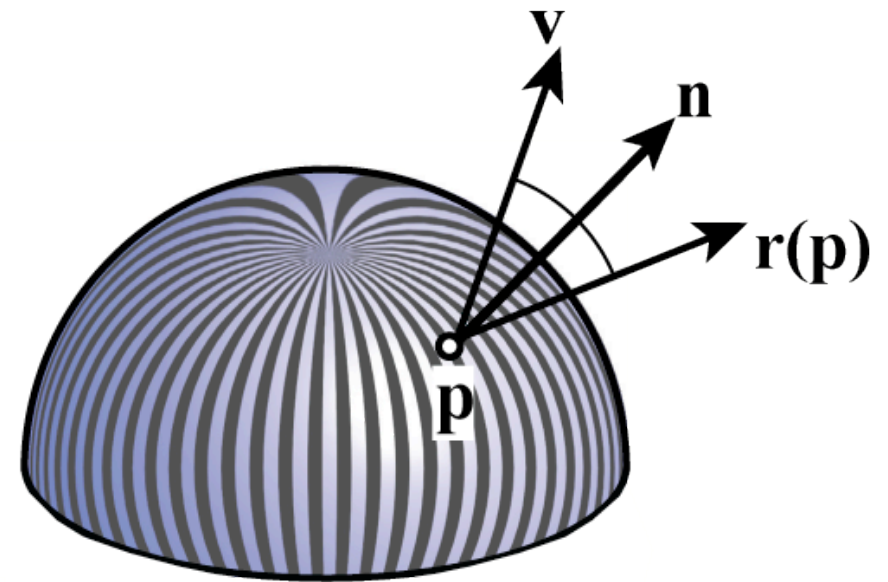
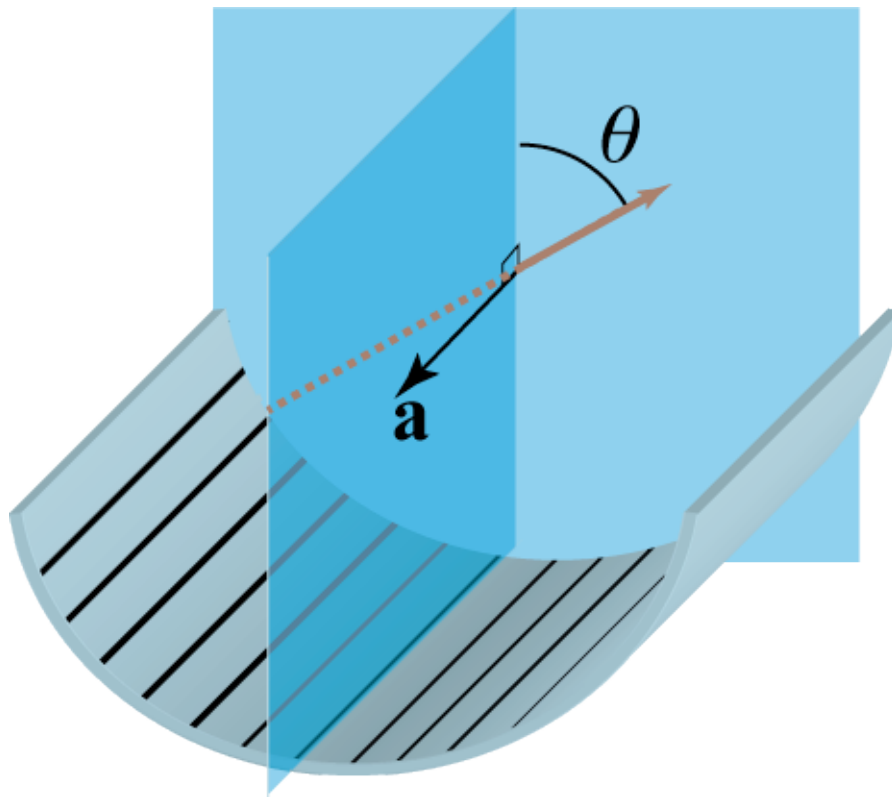
Reflection Line Function



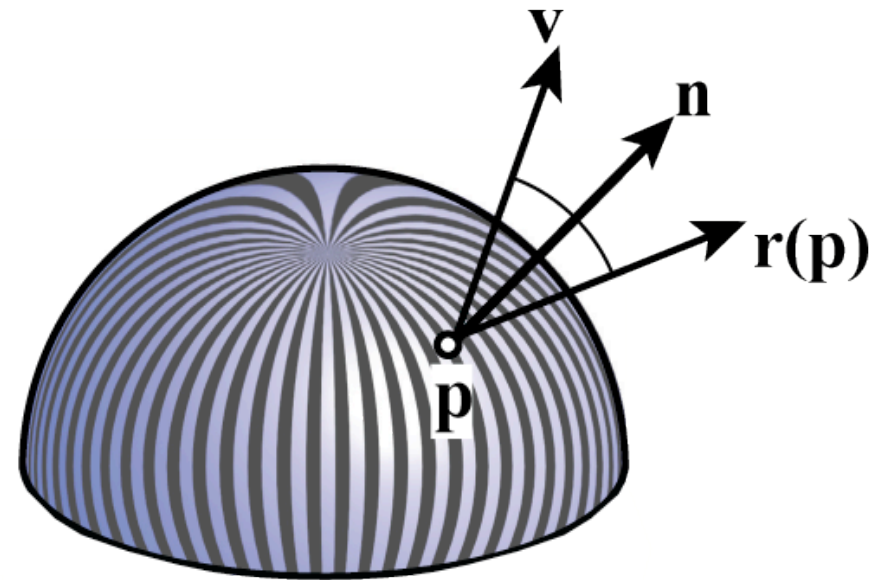
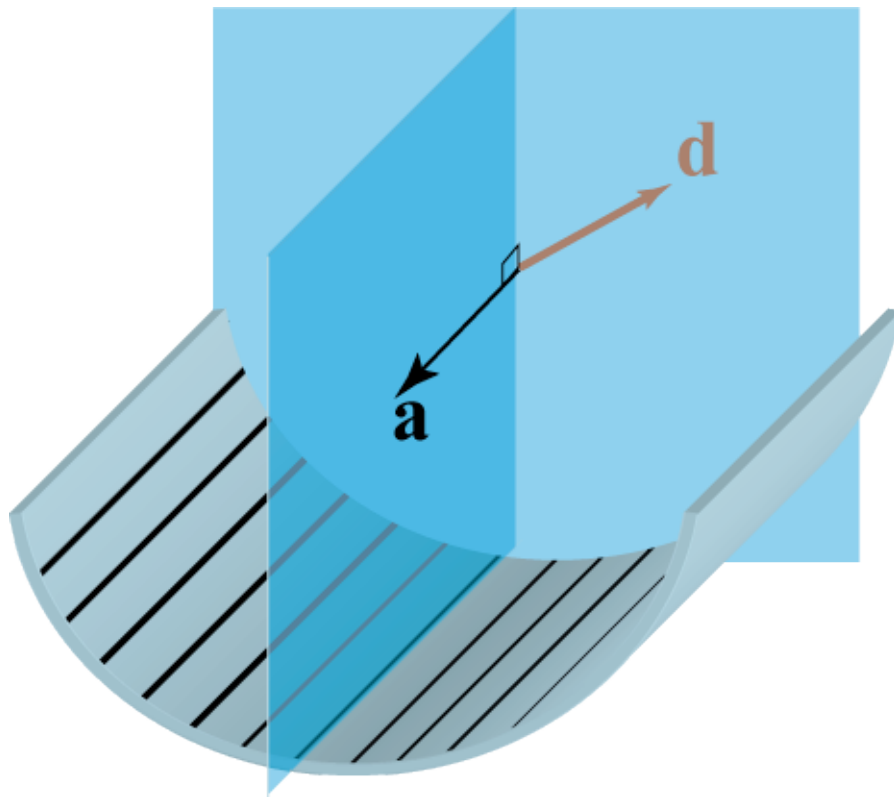
Reflection Line Function



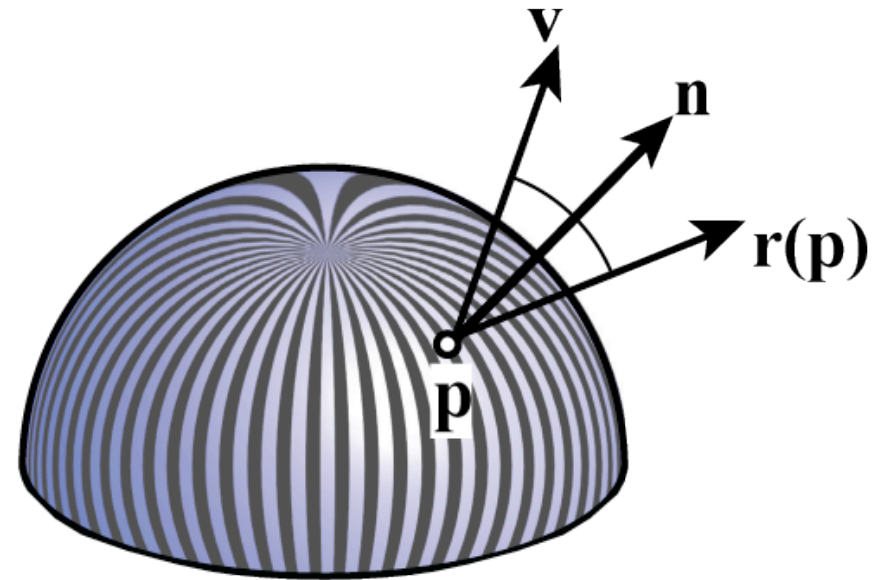
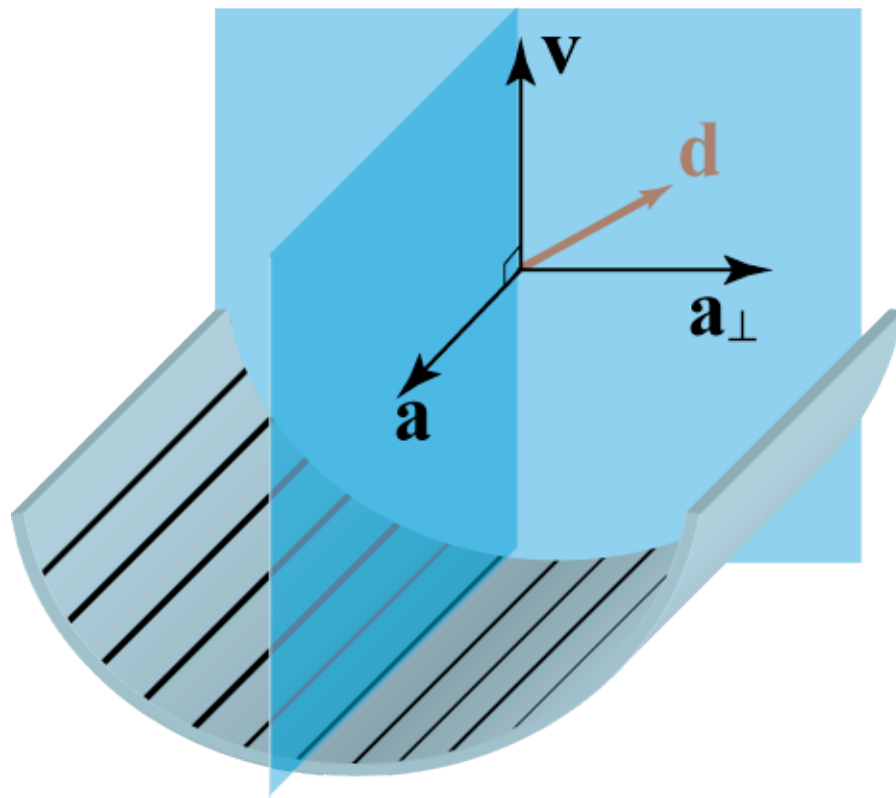
Reflection Line Function



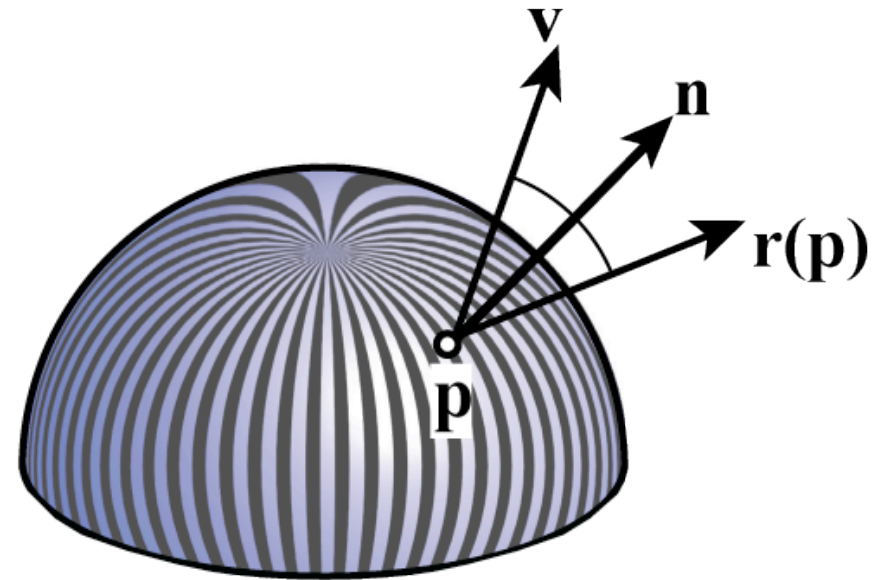
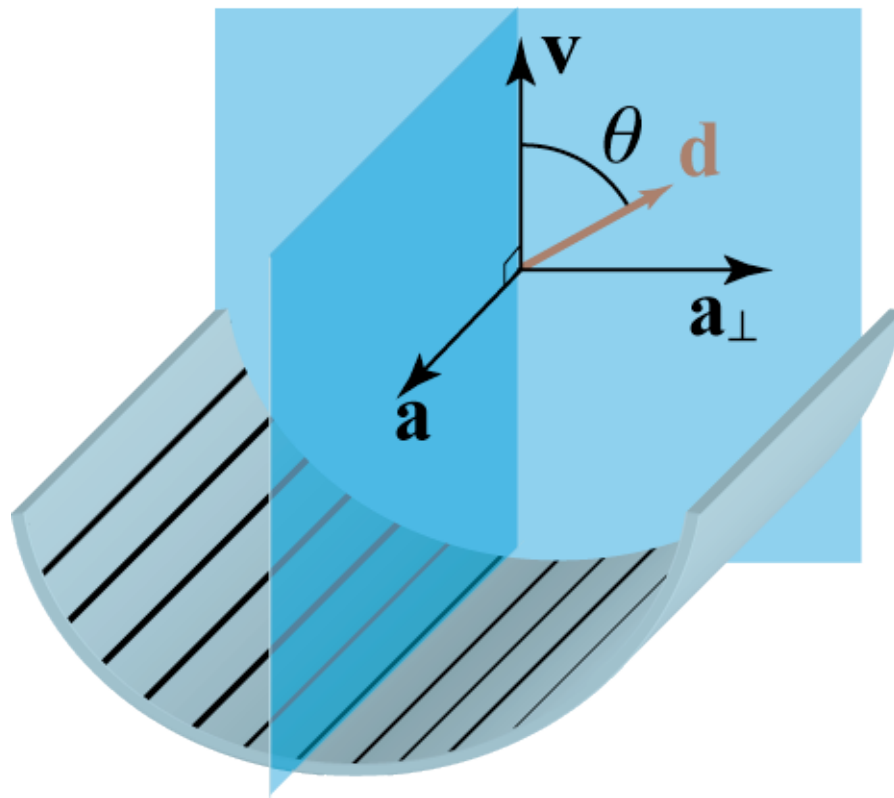
Reflection Line Function



Reflection Line Function

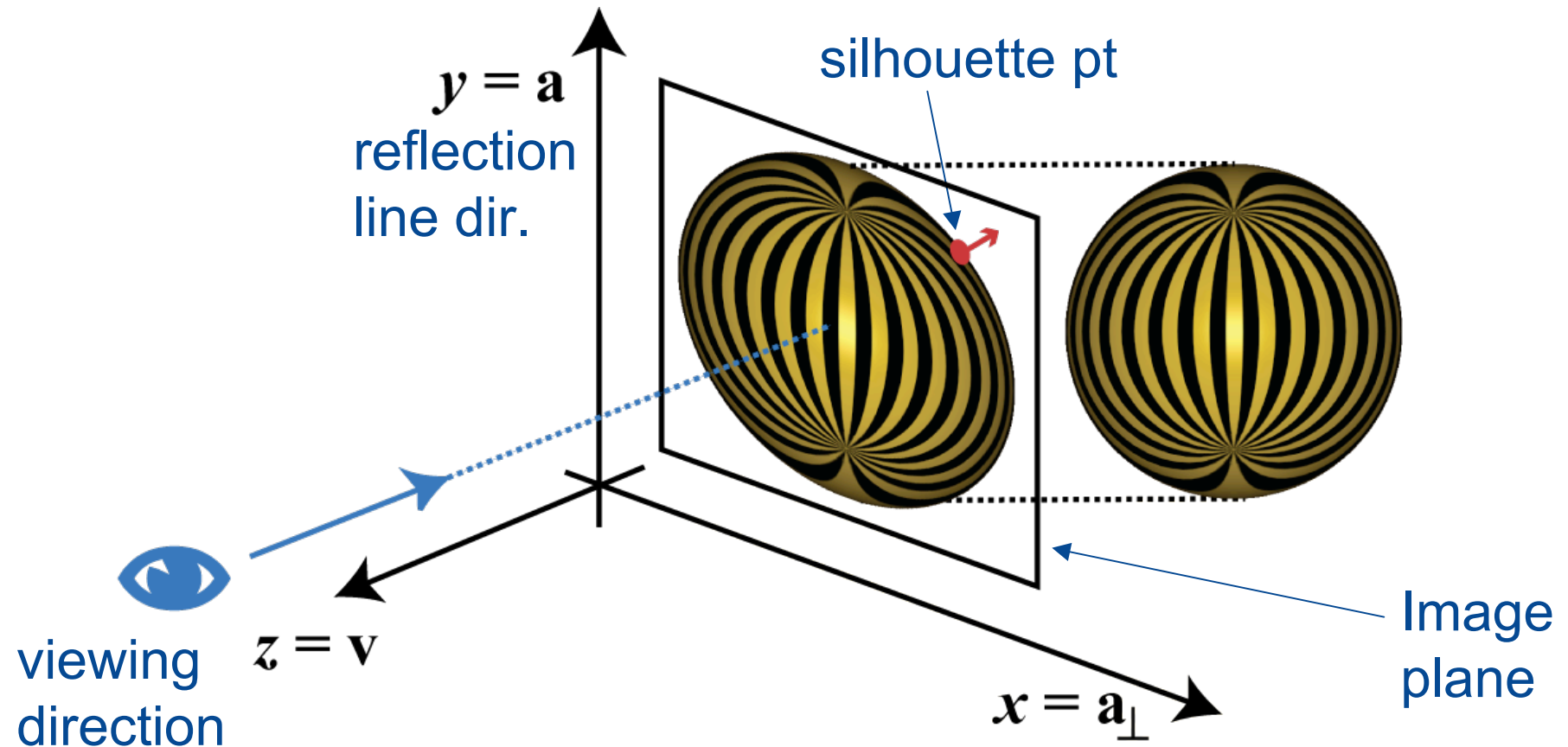


Reflection Line Function



$$\theta(\mathbf{p}) = \arctan((\mathbf{r}(\mathbf{p}) \cdot \mathbf{a}_\perp), (\mathbf{r}(\mathbf{p}) \cdot \mathbf{v}))$$

Image-Plane Parameterization



surface as height field

$$\theta(x, y) = \arctan(2f_x, (1 - f_x^2 - f_y^2))$$

Reflection Functionals

Function-based

$$\int_S (\cos \theta - \cos \theta^*)^2 + (\sin \theta - \sin \theta^*)^2 dx dy \rightarrow \min$$
$$\theta|_{\partial S} = \theta_0$$

User defined
reflection func.

Gradient-based

$$\int_S (\nabla \theta - \nabla \theta^*)^2 dx dy \rightarrow \min$$
$$\theta|_{\partial S} = \theta_0, \frac{\partial}{\partial n} \theta|_{\partial S} = \varphi_0$$

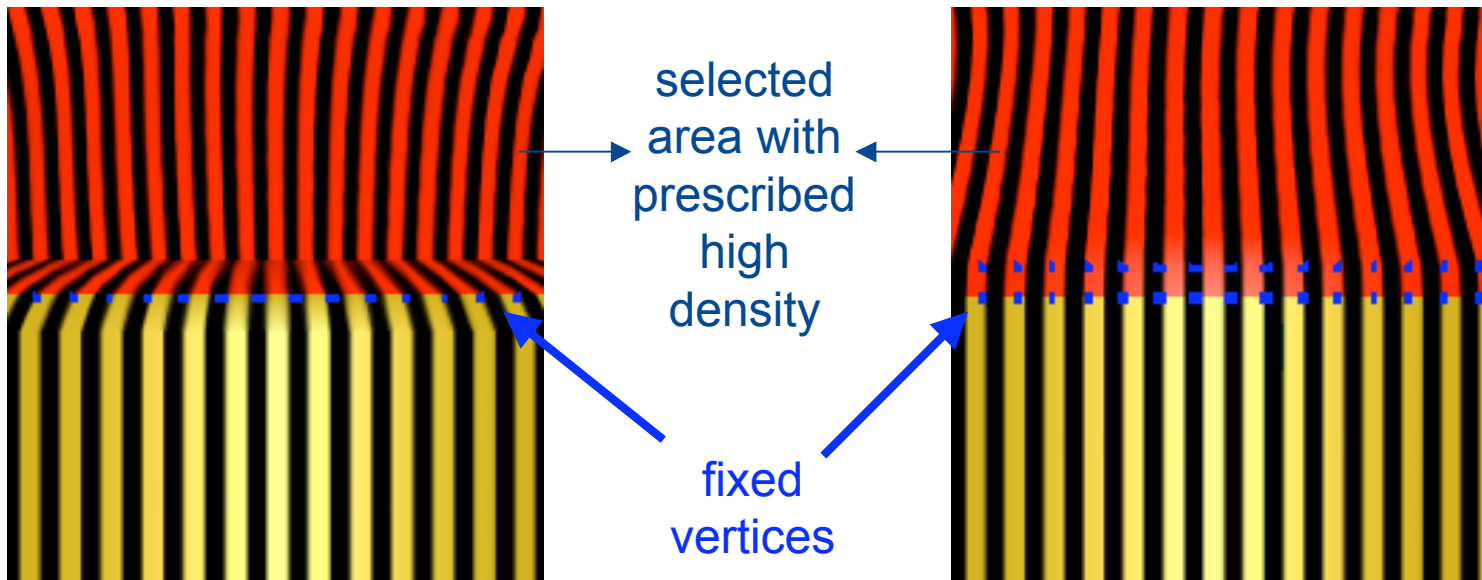
Reflection Functionals

Function-based

- Euler-Lagrange 2nd order
- Can prescribe only function values on boundary
- No blending with rest of surface

Gradient-based

- Euler-Lagrange 4th order
- Can prescribe function and derivative values on boundary
- Smooth blending at selection boundaries



Gradient Discretization

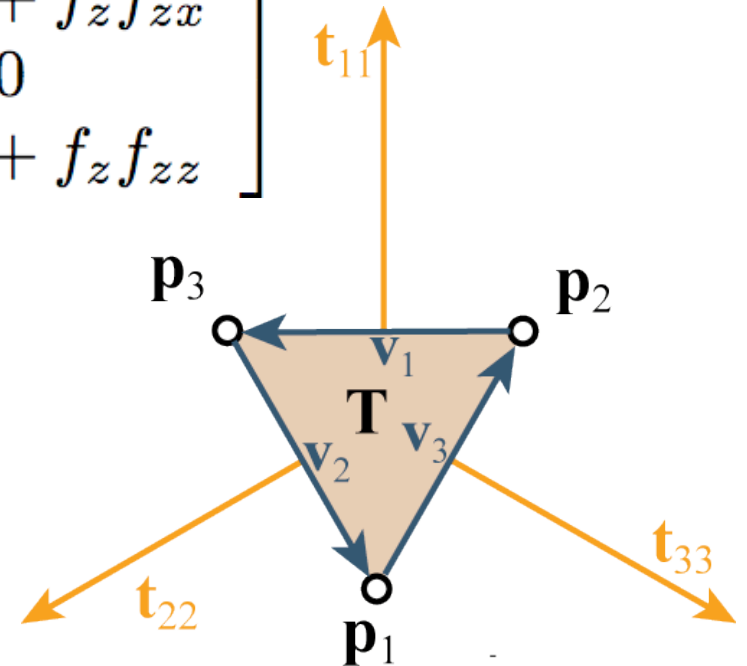
$$\nabla \theta = \frac{a \nabla b - b \nabla a}{a^2 + b^2} \quad a = 2f_x, \quad b = 1 - f_x^2 - f_z^2$$

$$\nabla a = 2 \begin{bmatrix} f_{xx} \\ 0 \\ f_{xz} \end{bmatrix}, \quad \nabla b = -2 \begin{bmatrix} f_x f_{xx} + f_z f_{zx} \\ 0 \\ f_x f_{xz} + f_z f_{zz} \end{bmatrix}$$

Triangle-centered

Piecewise linear finite elements

$$\nabla_{discr} f_T = \frac{1}{2A} \sum_{i=1,2,3} f(\mathbf{p}_i) \mathbf{t}_{ii}$$



Hessian Discretization

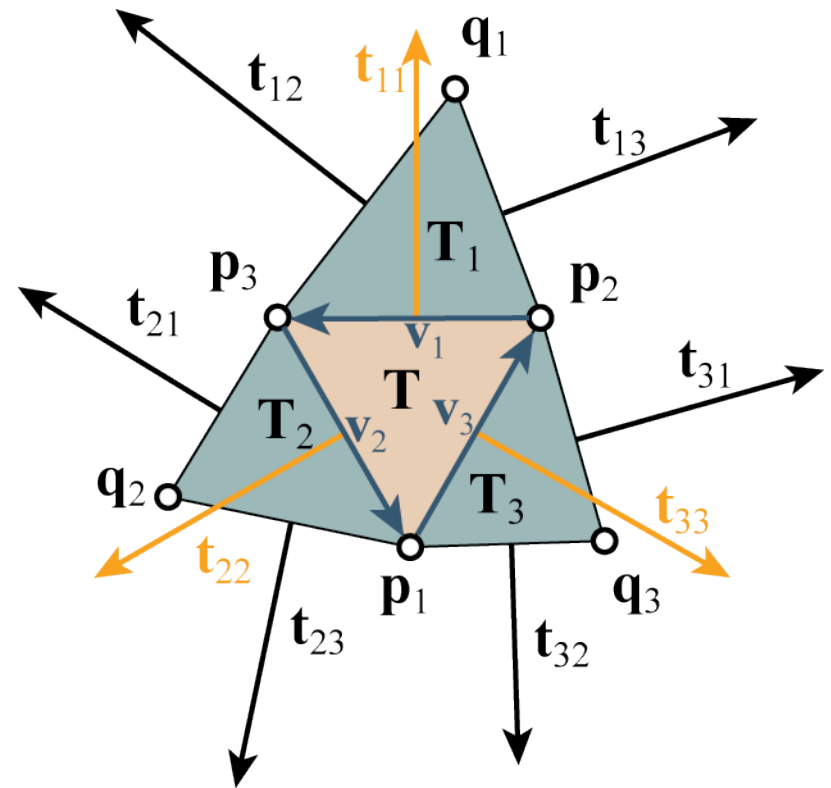
At least 6 DOF per stencil needed -- triangle with flaps

Triangle-averaged

Averaging shape operators over triangle edges

[Hildebrandt et al. 2005],

[Grinspun et al. 2006]



Hessian Discretization

At least 6 DOF per stencil needed -- triangle with flaps

Triangle-averaged

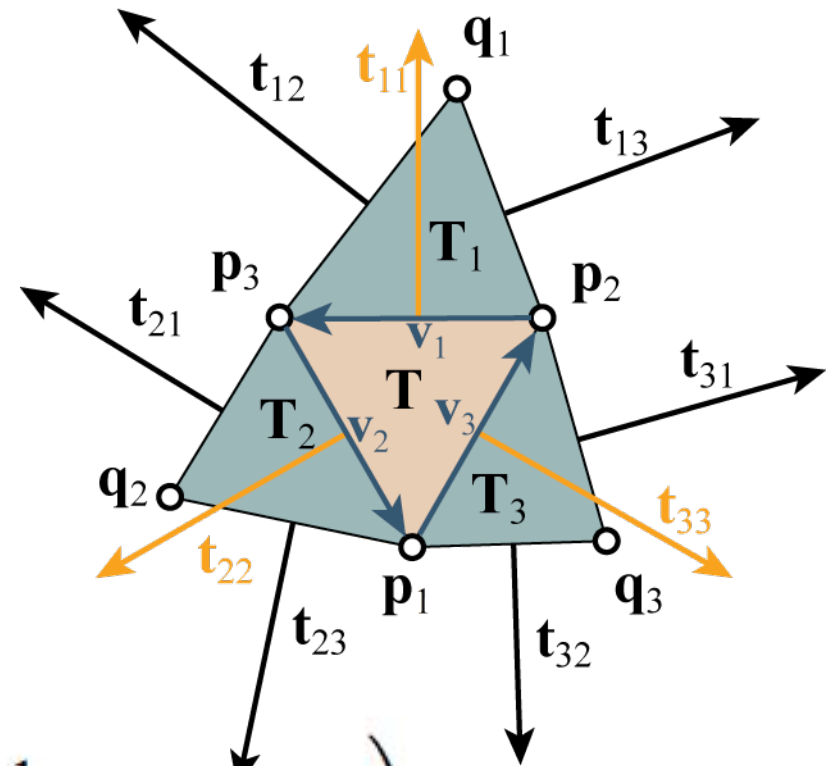
Averaging shape operators over triangle edges

[Hildebrandt et al. 2005],

[Grinspun et al. 2006]

A, A_i : area factors

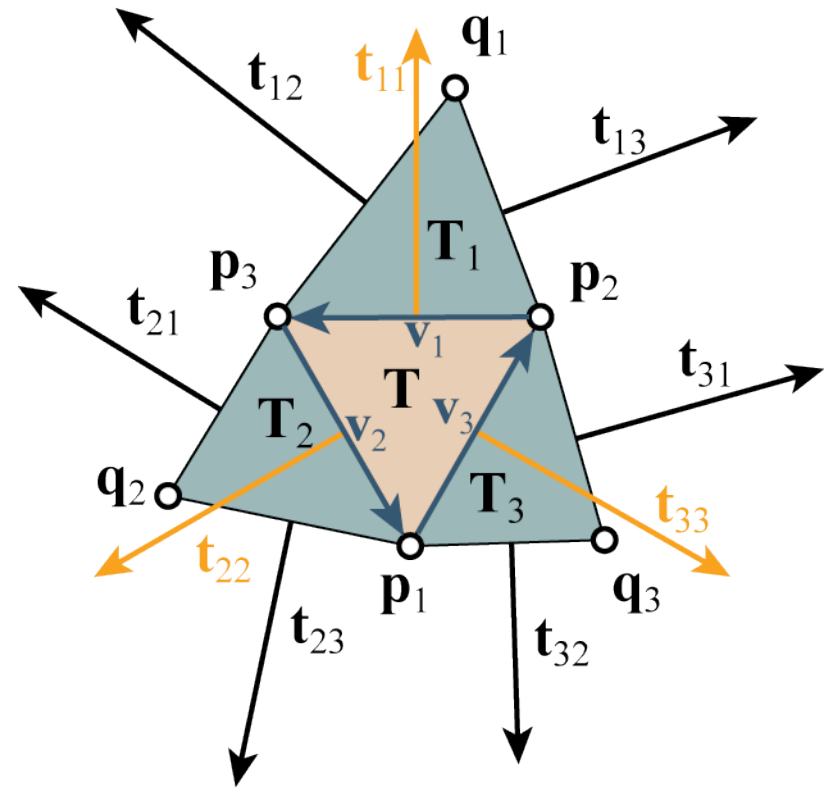
$$H(f) = \frac{1}{A} \left(\sum_{i,j,j \neq i} \frac{1}{A_j} f(\mathbf{q}_j) \mathbf{t}_{ii} \otimes \mathbf{t}_{ij} + \sum_i \frac{1}{A_i} f(\mathbf{p}_i) \mathbf{t}_{ii} \otimes \mathbf{t}_{ii} \right)$$



Hessian Discretization

Triangle-averaged

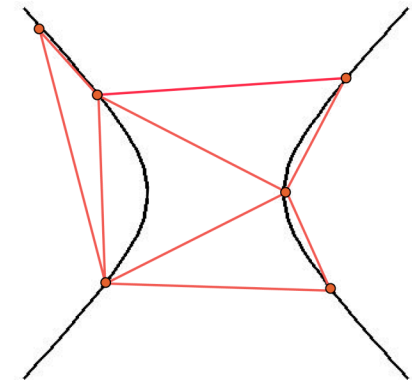
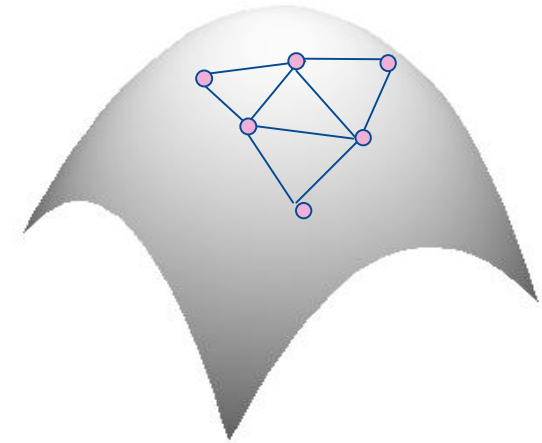
- Pros
 - robust
 - simple
 - consistent for special meshes.
- Cons
 - for general meshes, mesh-dependent error



Hessian Discretization

Quadratic interpolation

- Unique quadratic function to interpolate vertices of stencil
 - Use quadratic term coefficients
-
- Pros
 - Consistent
 - Less dependent on mesh connectivity
 - Cons
 - Less robust - if vertices on or close to a conic no solution or large coefficients



Hessian Discretization

Hybrid discretization

- Use triangle-averaged scheme when quadratic interpolation unstable
- Evaluate stability by comparing coeffs to $1/l_{max}^2$
- Pros:
 - More robust
 - More accurate
- Cons:
 - Large errors for some meshes

Hessian Discretization



Initial



Quad fit

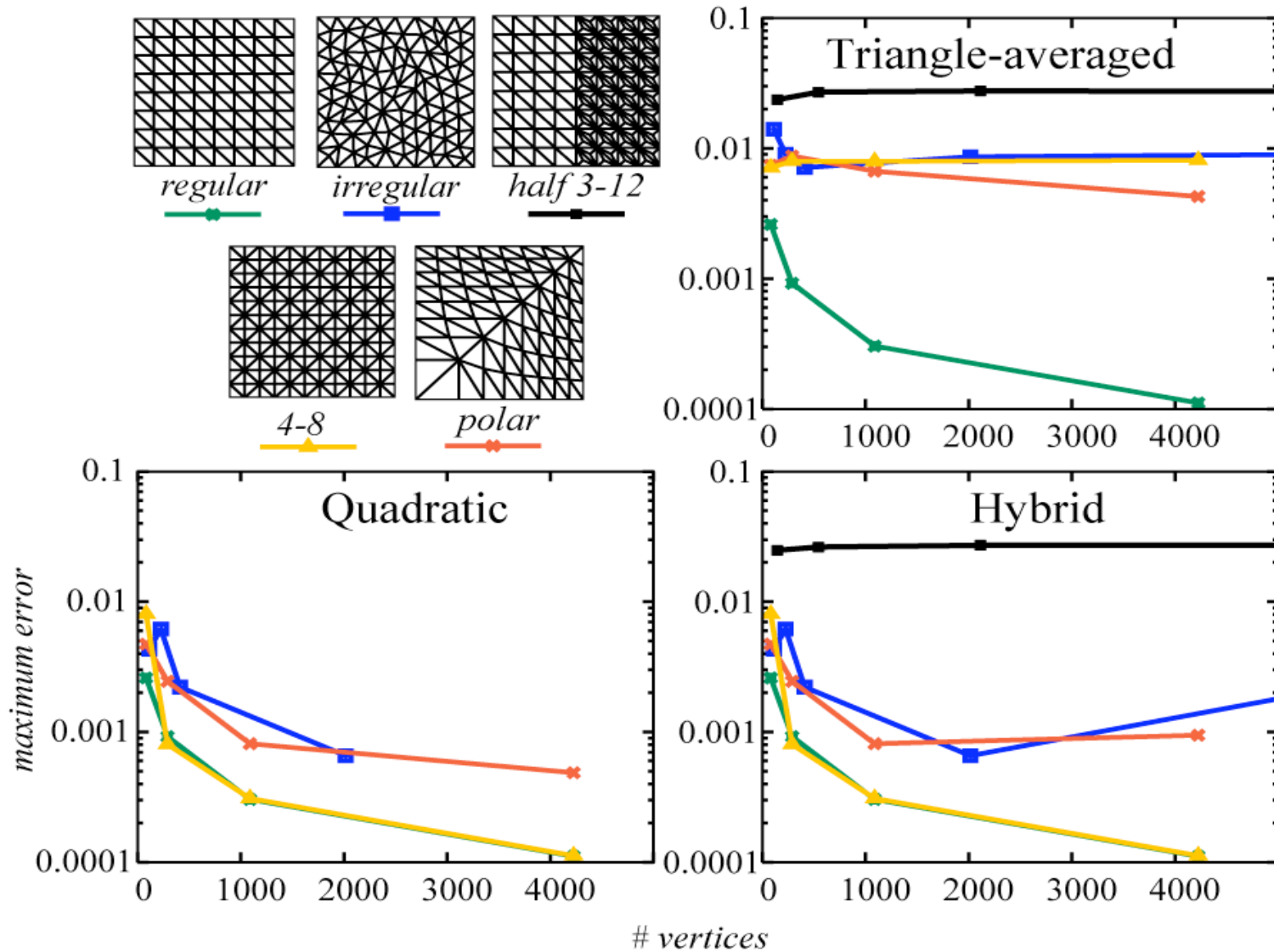


Tri-avg

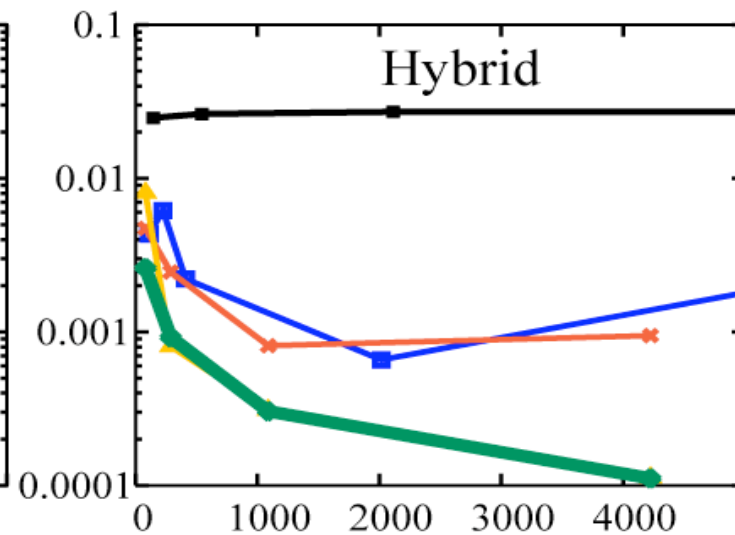
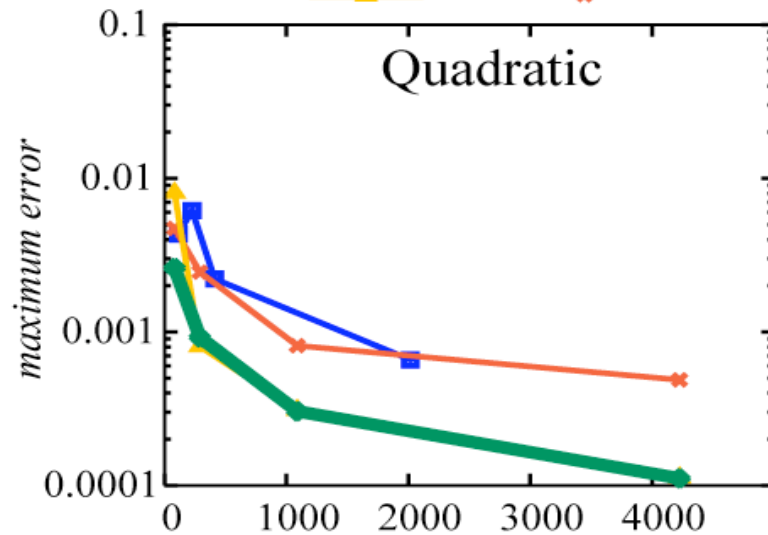
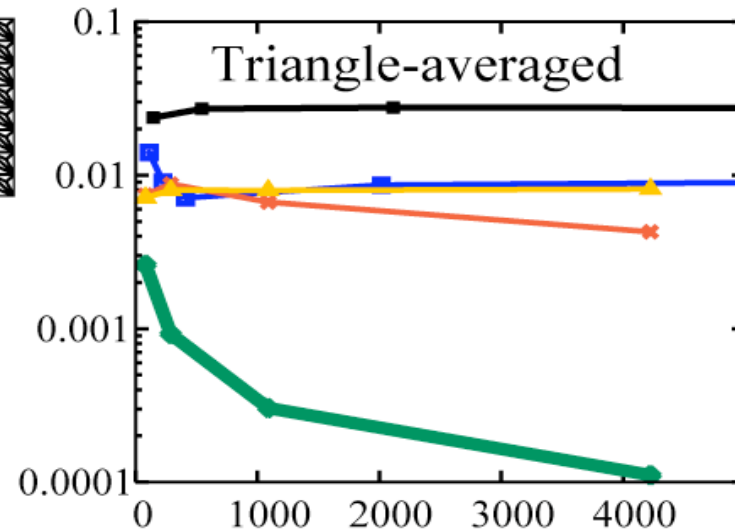
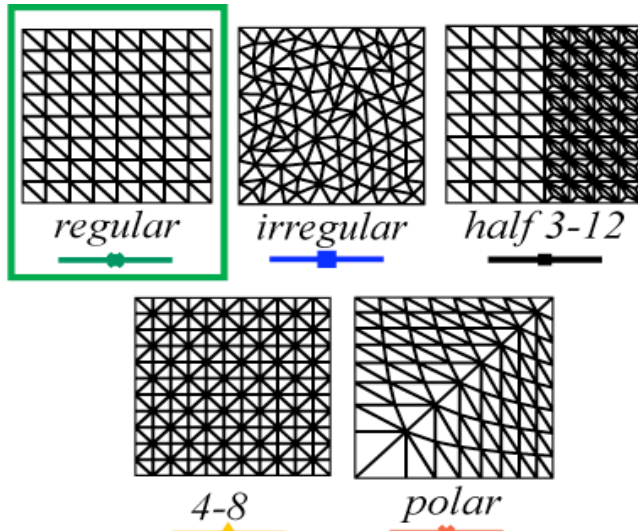


Hybrid

Hessian Discretization

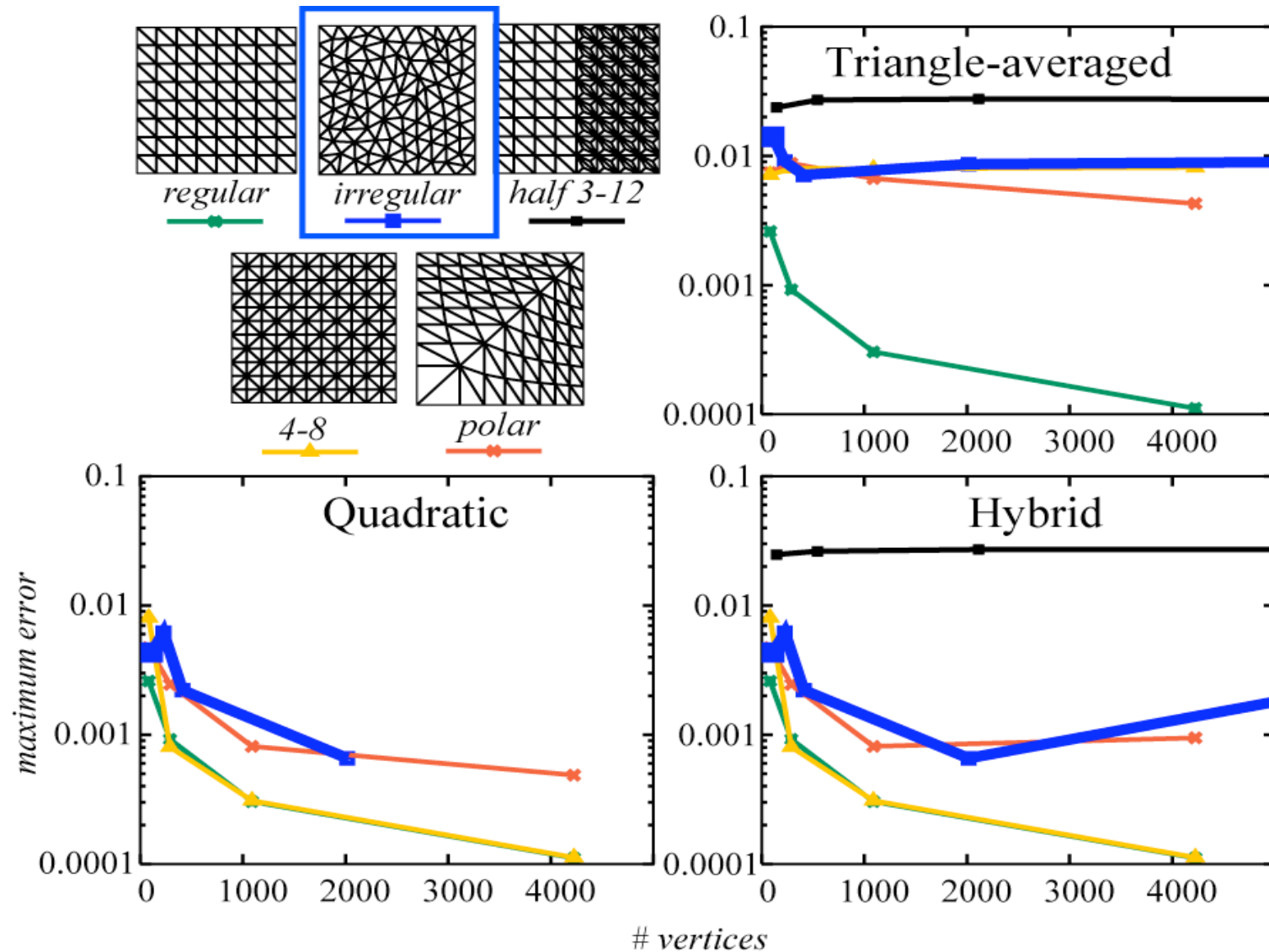


Hessian Discretization

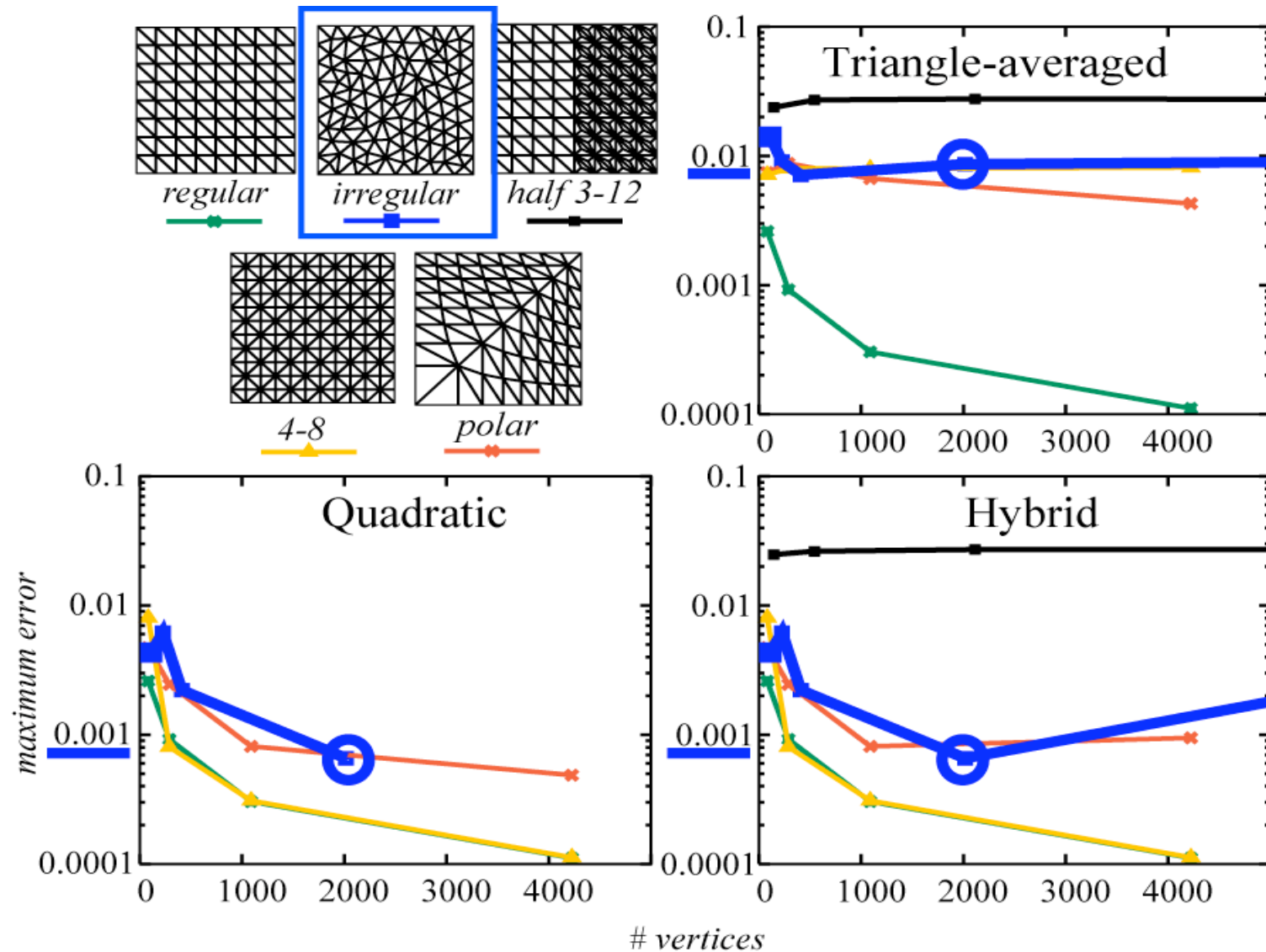


vertices

Hessian Discretization



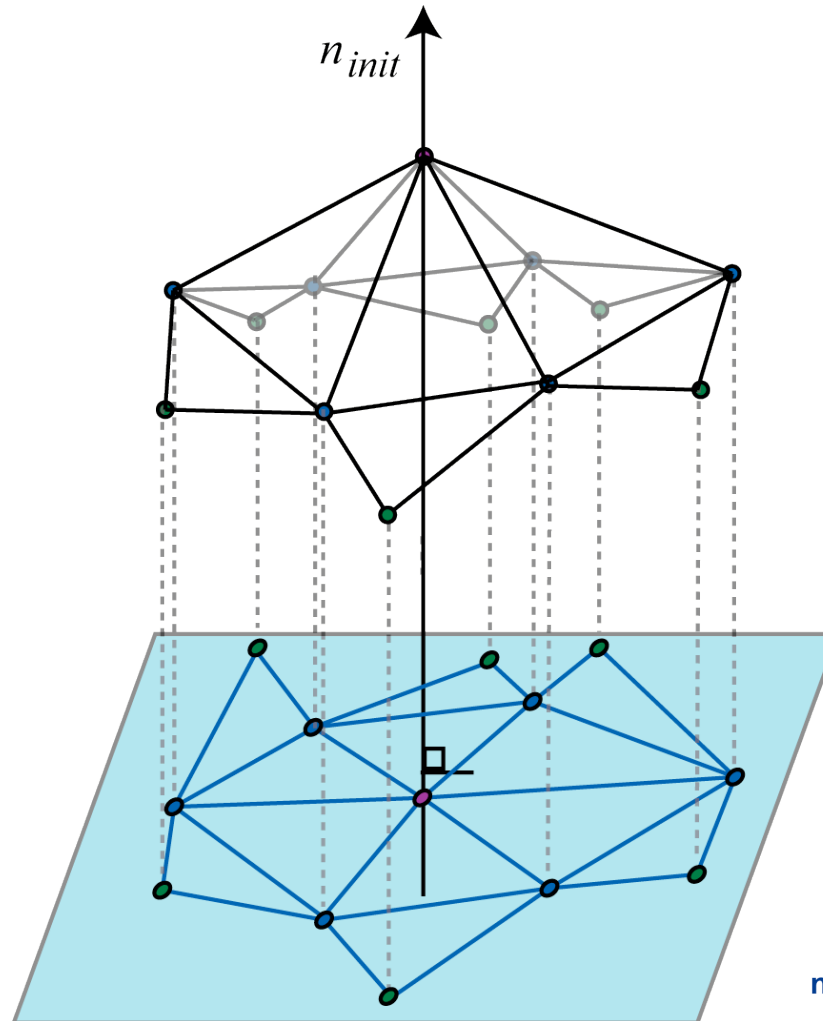
Hessian Discretization



Normal Estimation

Local quadratic fit
($O(h^2)$)

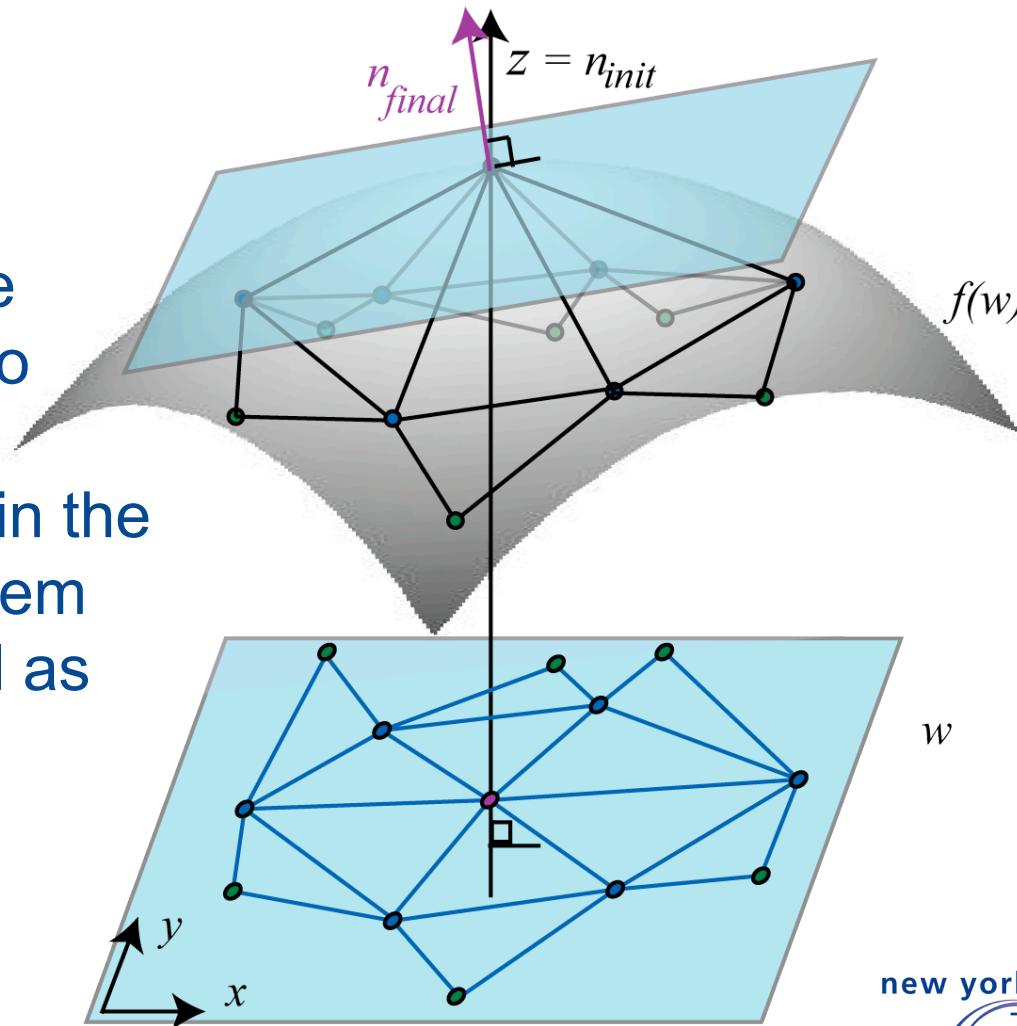
1. Project to plane perpendicular to initial normal



Normal Estimation

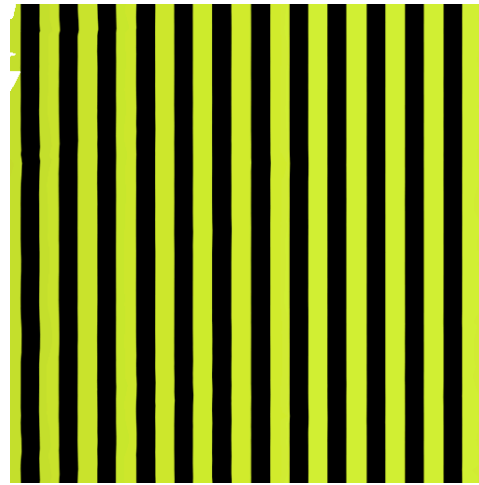
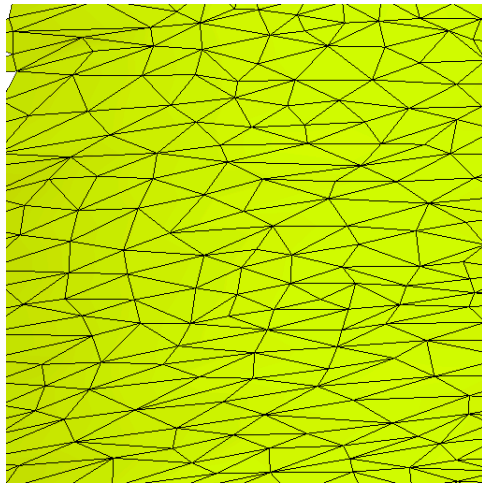
Local quadratic fit
($O(h^2)$)

1. Project to plane perpendicular to initial normal
2. Fit a quadratic in the new coord system
3. Use the normal as vertex normal



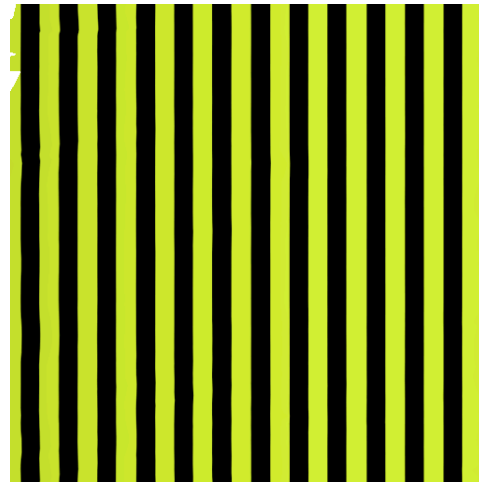
Normal Estimation

mesh



analytic
normals

averaged
face
normals



quadratic fit
normals

Interactive Speeds

- Linearizing the energy does not work
- Full non-linear Newton or gradient-only methods too expensive

Solution:

Inexact Newton method with line search

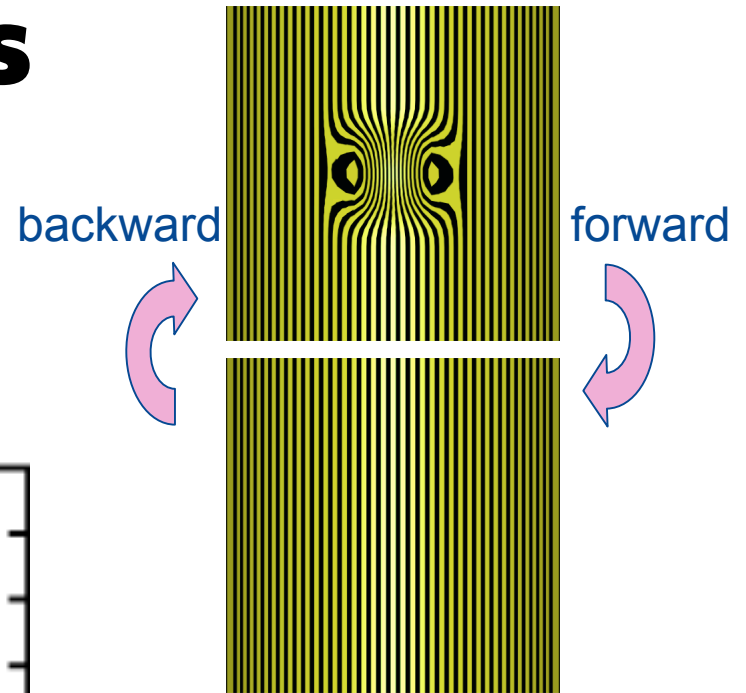
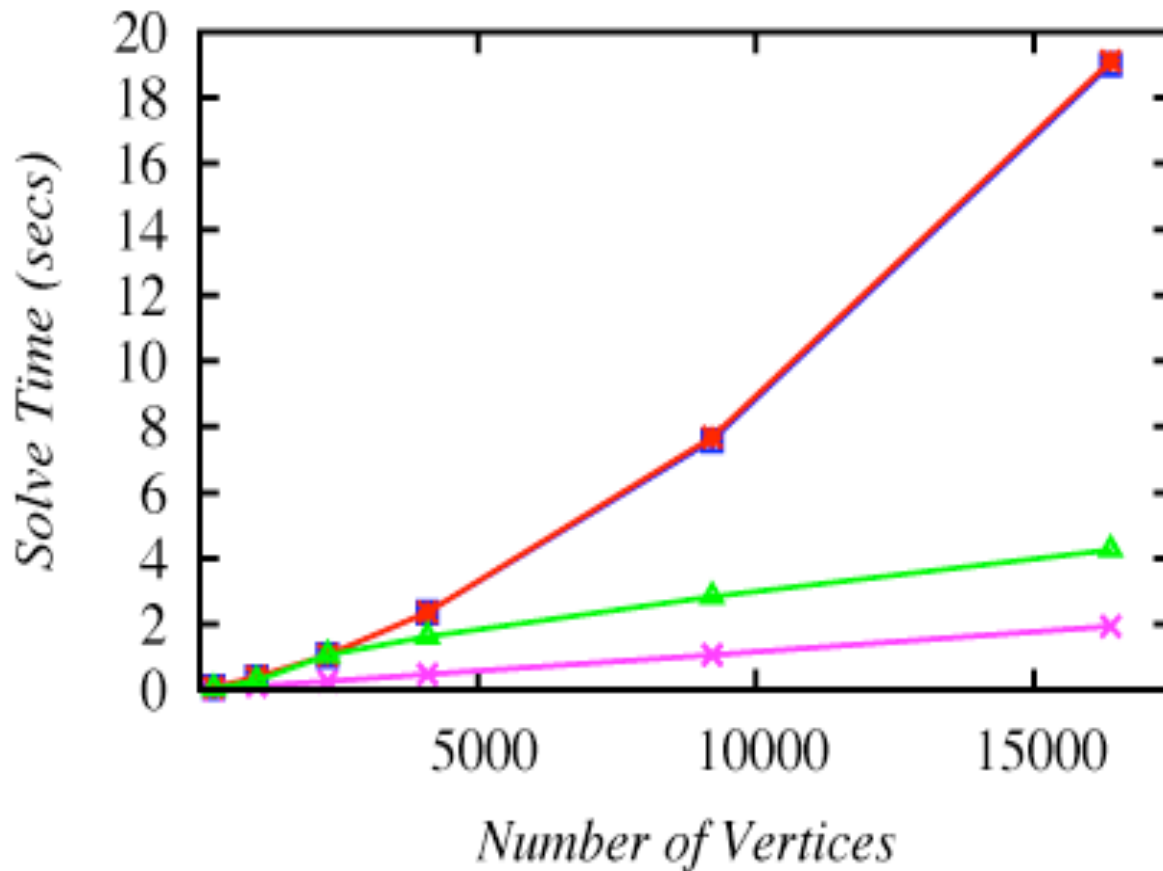
- Compute and factor Hessian once and reuse
- Compute Hessian for the linearized problem

$$\theta_{lin}(x, y) = 2f_x$$

Interactive Speeds

- Forward Hessian always —■—
- Forward Hessian once —×—
- Backward Hessian always —*—
- Backward Hessian once —▲—

Solve Times v. Num Vertices



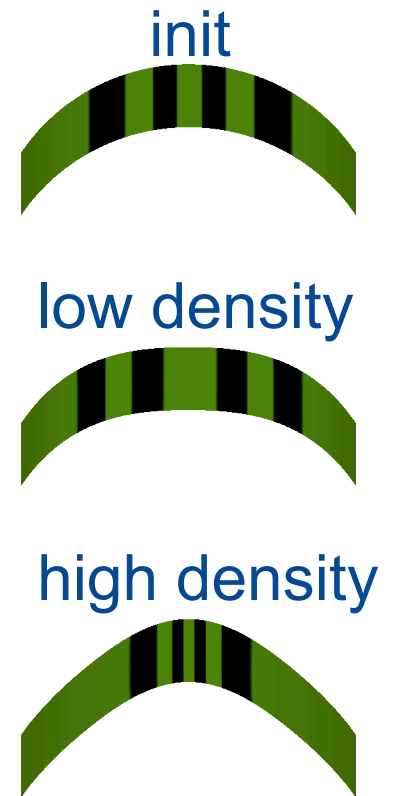
5x Gain
10x Gain

Reflection Line Manipulation

Changing density

[Line density Movie - WMV](#)

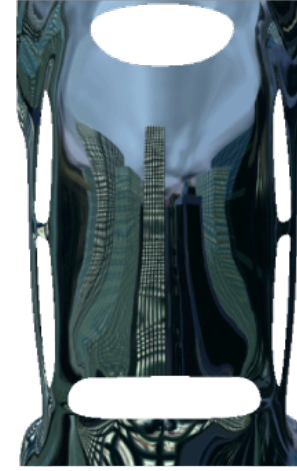
[Line density Movie - MP4](#)



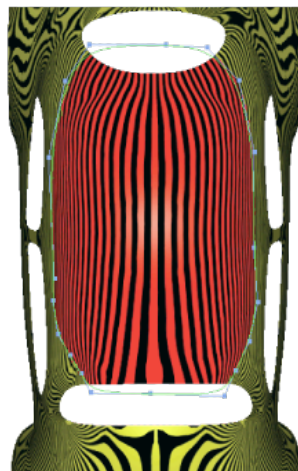
Reflection Line Manipulation

Changing density

low
density



high
density



Reflection Line Manipulation

Changing direction

[Rotation Movie](#) - WMV

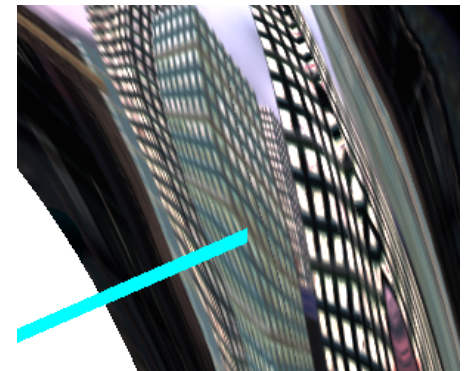
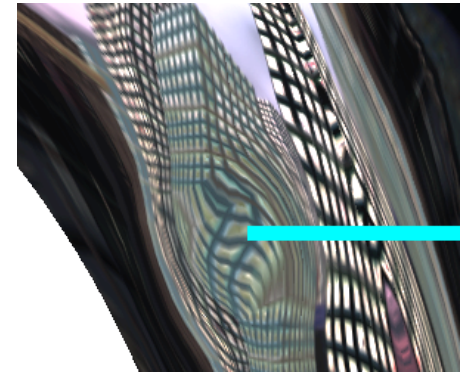
[Rotation Movie](#) – MP4

Reflection Line Manipulation

Changing direction

[Car example movie - WMV](#)

[Car example movie - MP4](#)

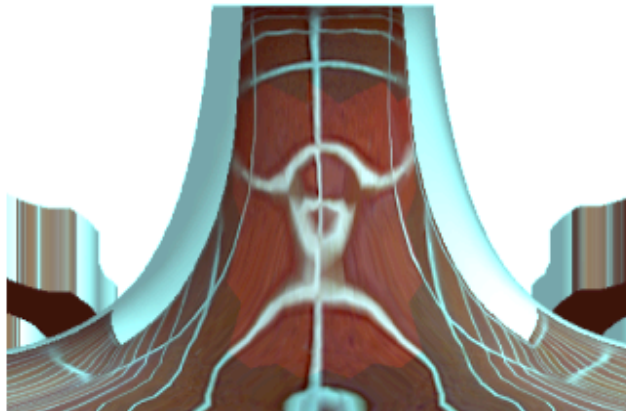
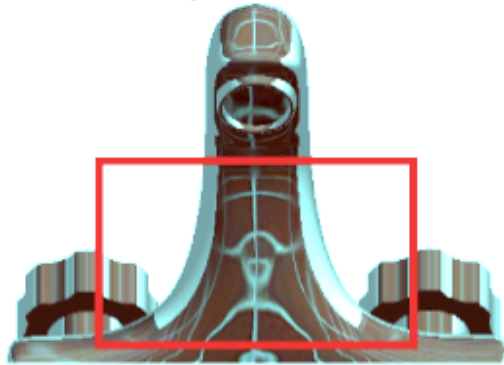


Reflection Line Manipulation

Smoothing reflection lines

- Target values through smoothing

before

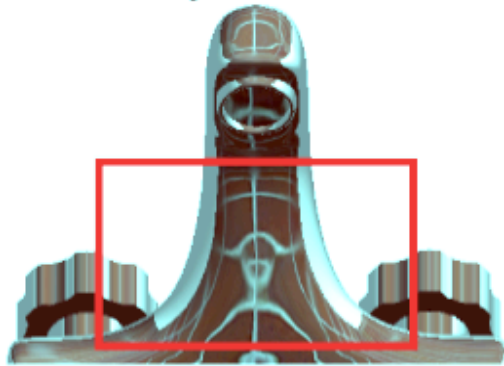


Reflection Line Manipulation

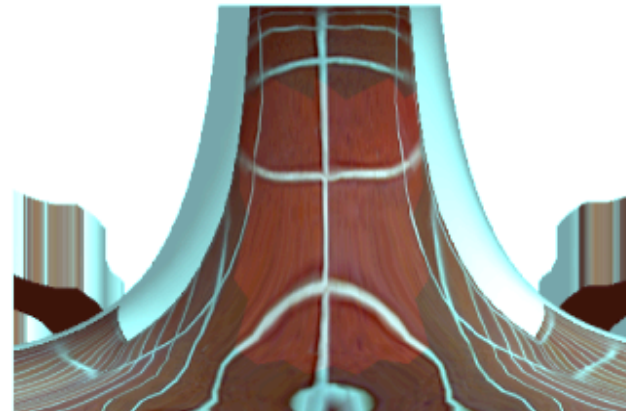
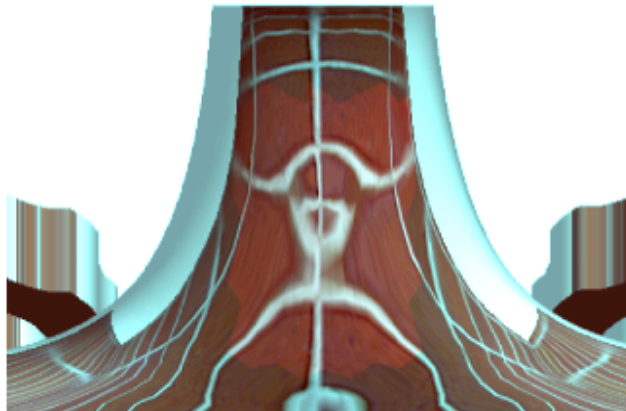
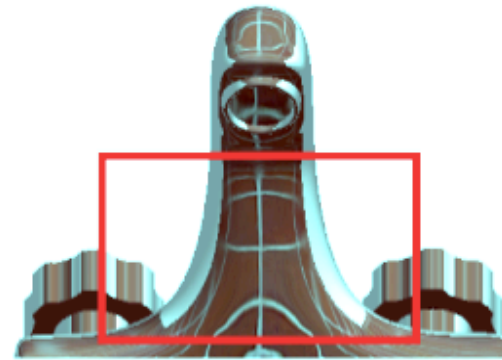
Smoothing reflection lines

- Target values through smoothing

before



after

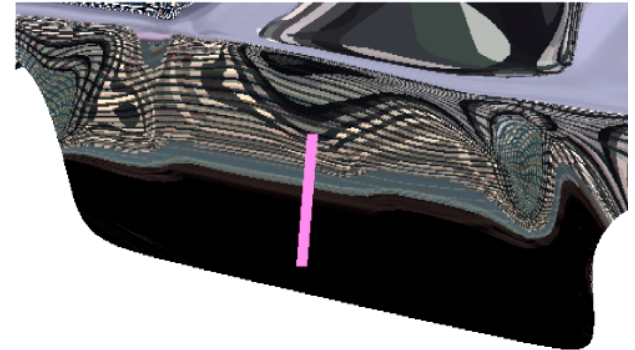
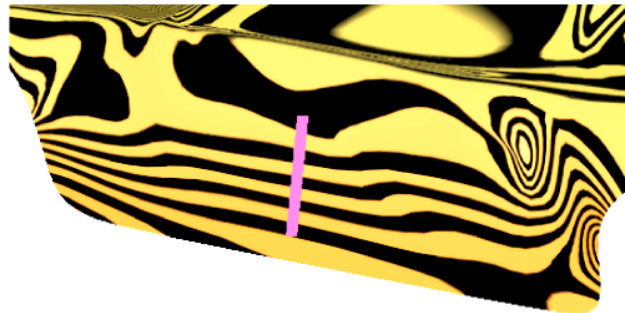
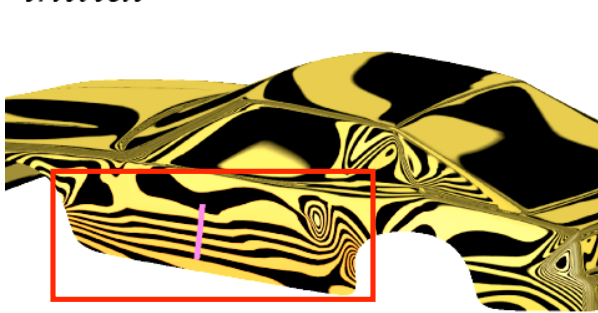


Reflection Line Manipulation

Smoothing reflection lines

- Target values through smoothing
- Directional smoothing

initial

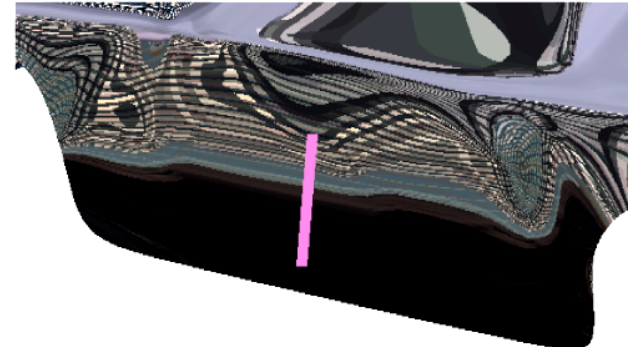
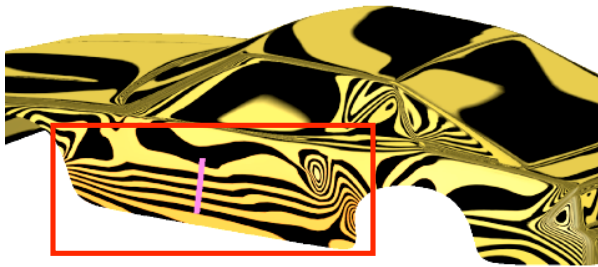


Reflection Line Manipulation

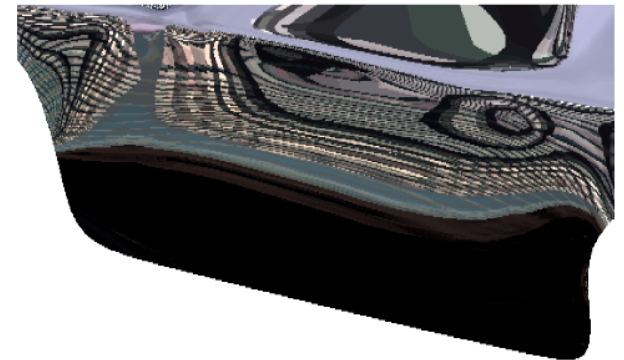
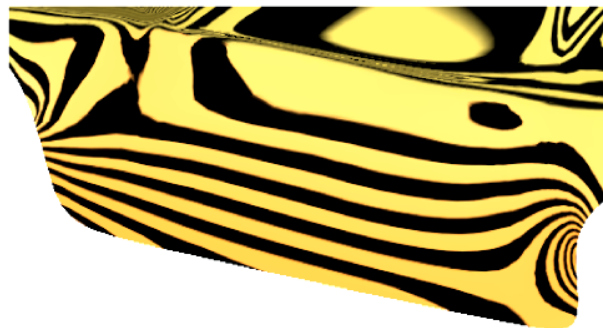
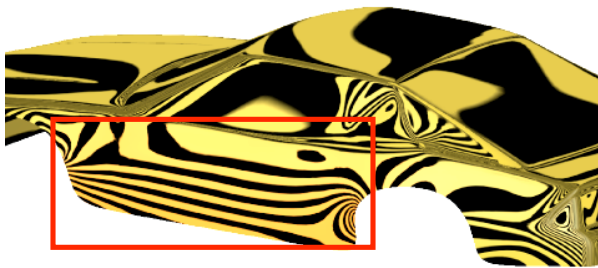
Smoothing reflection lines

- Target values through smoothing
- Directional smoothing

initial

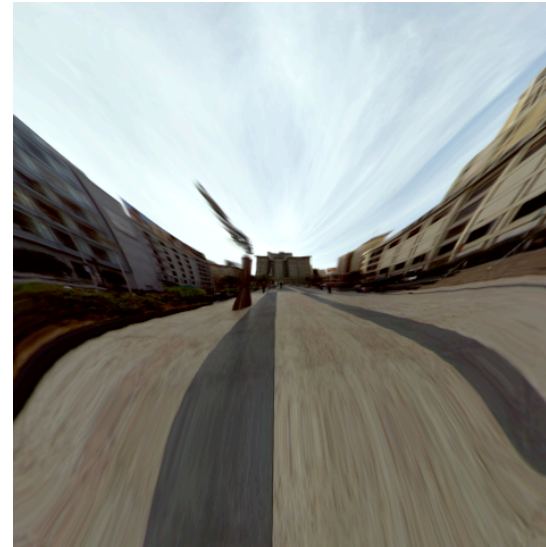
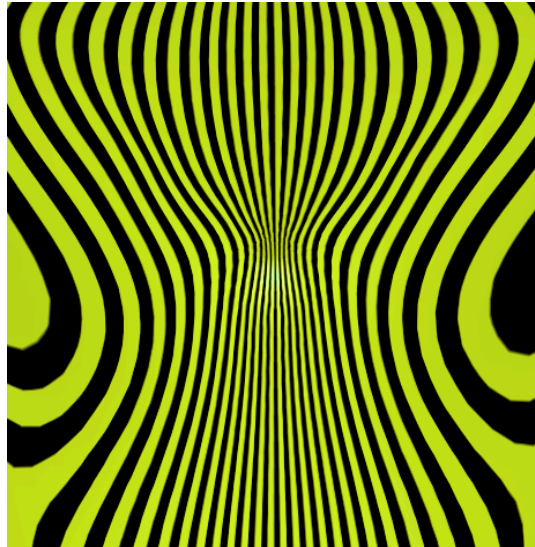
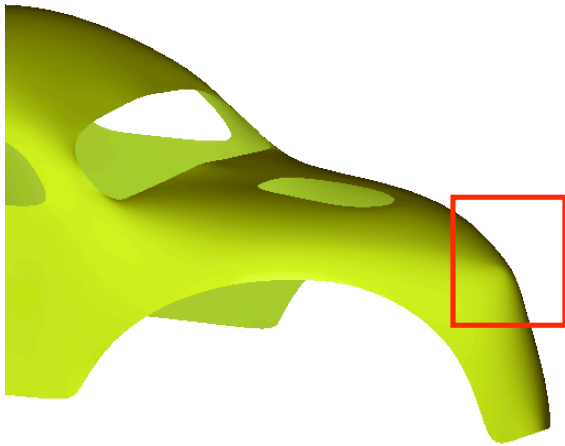


reflection functional



Reflection Line Manipulation

Warping



Reflection Line Manipulation

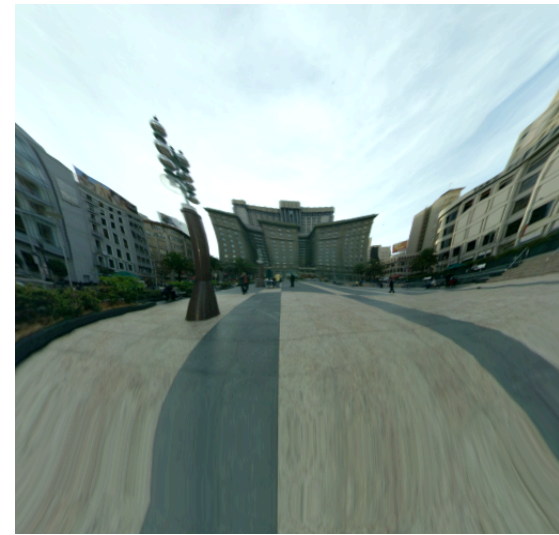
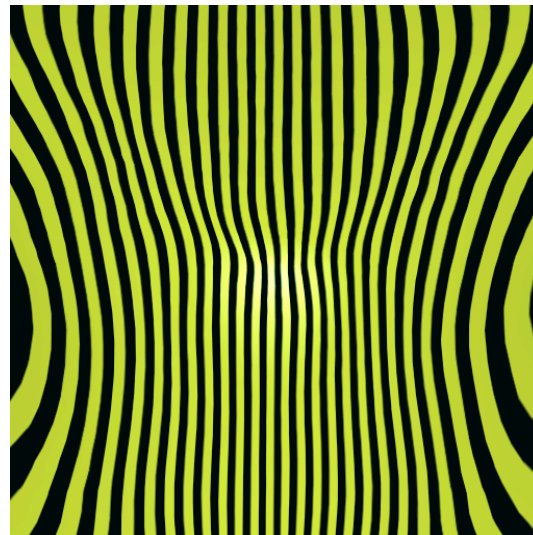
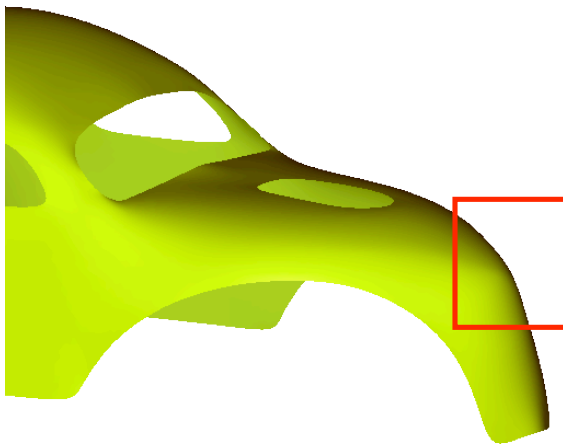
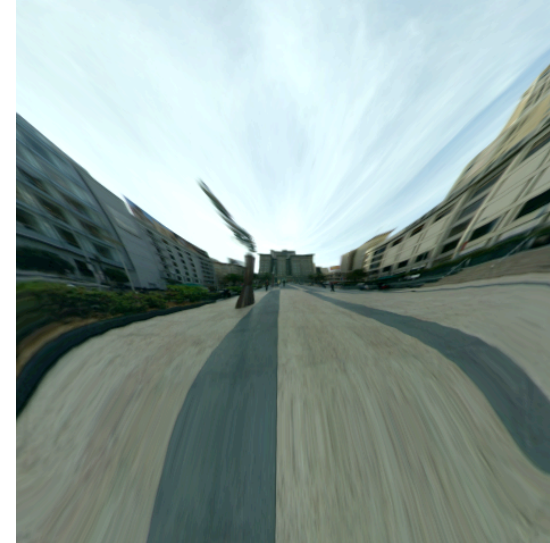
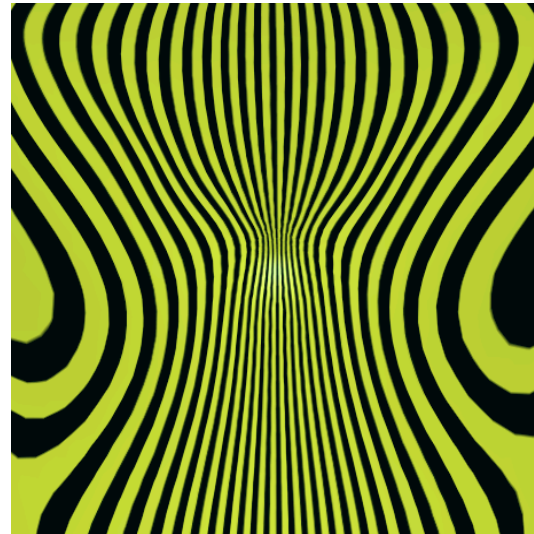
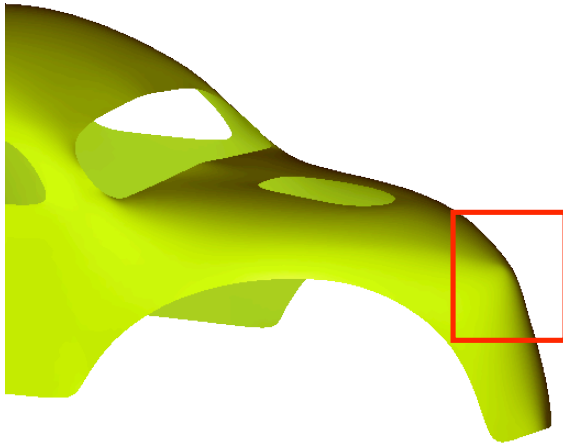
Warping

[Warping on car movie - WMV](#)

[Warping on car movie – MP4](#)

Reflection Line Manipulation

Warping



Reflection Line Manipulation

Image based reflection pattern



reflection function



reflection lines



original *blurred*



environment map

Conclusions/Future Work

Interactive system to optimize shapes of surfaces based on reflection lines

- Image-plane parameterization
- Simple triangle-based Hessian discretization

Future Work

- Integration with silhouette editing of [Nealen, Sorkine, Alexa and Cohen-Or 2005]

Acknowledgements

- Robb Bifano
- Eitan Grinspun
- Jeff Han
- Harper Langston
- Ilya Rosenberg
- SGP Reviewers

This work is partially supported by award NSF CCR-0093390, IBM Faculty Partnership Award and a Rudin Foundation Fellowship